

[Horizontal Lidar] Map scanning, locating and obstacle avoidance

[Front RGB Camera]

Cruising with cleaning, obstacle avoidance and capture real-time colorful image.

[Tilt Camera]

Ranging, obstacle avoidance and capture real-time colorful image.

[Fill-in Light]

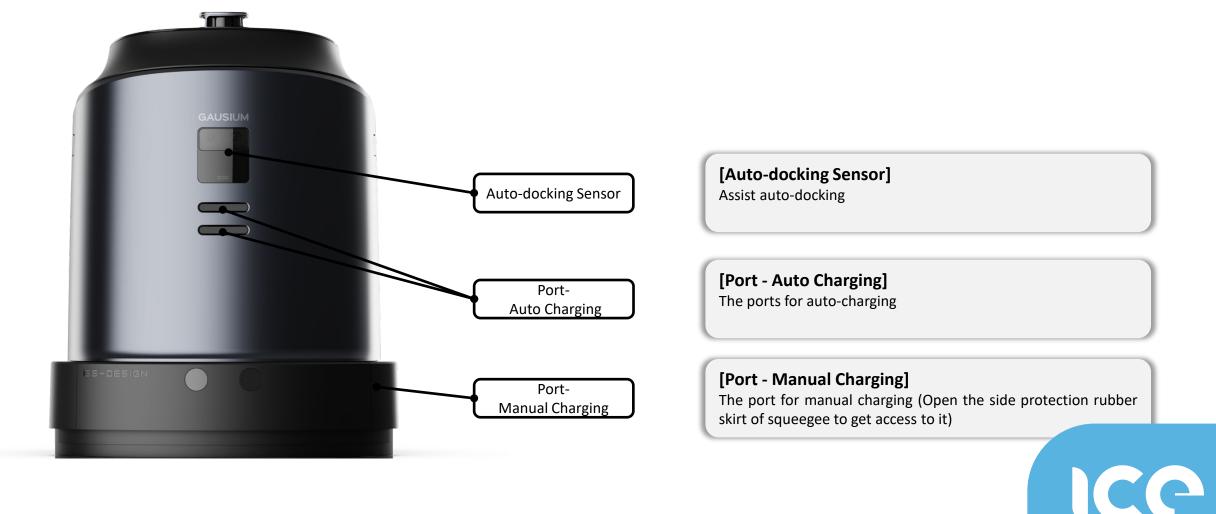
Fill in the light for front camera to assist cruising.

[Squeegee Assembly]

Scrubbing the floor and absorbing water stain.

[Tile Laser]

Obstalce avoidance and ranging.

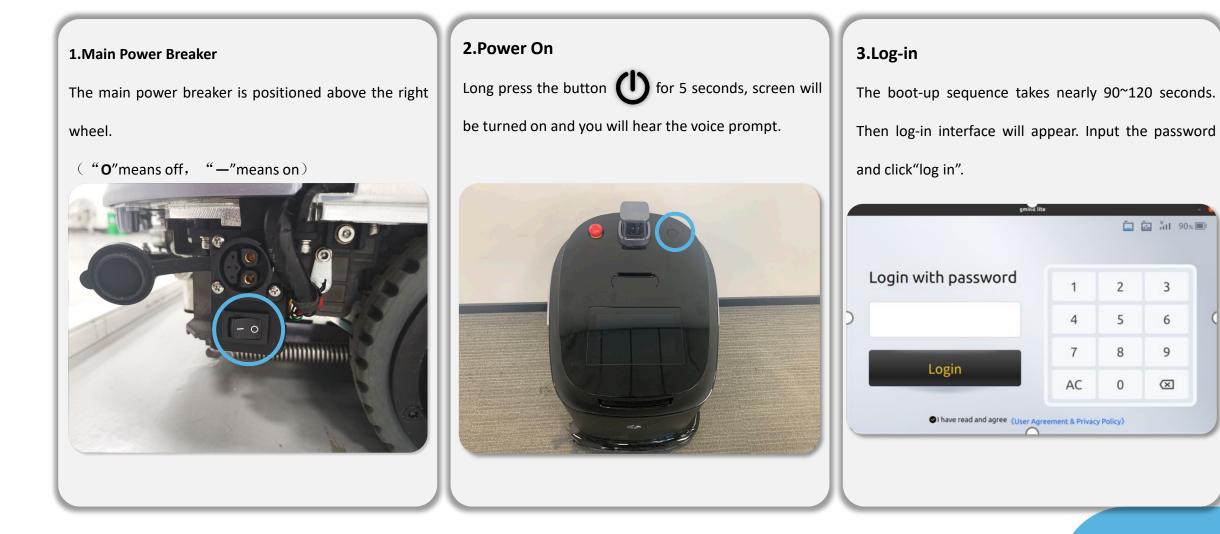


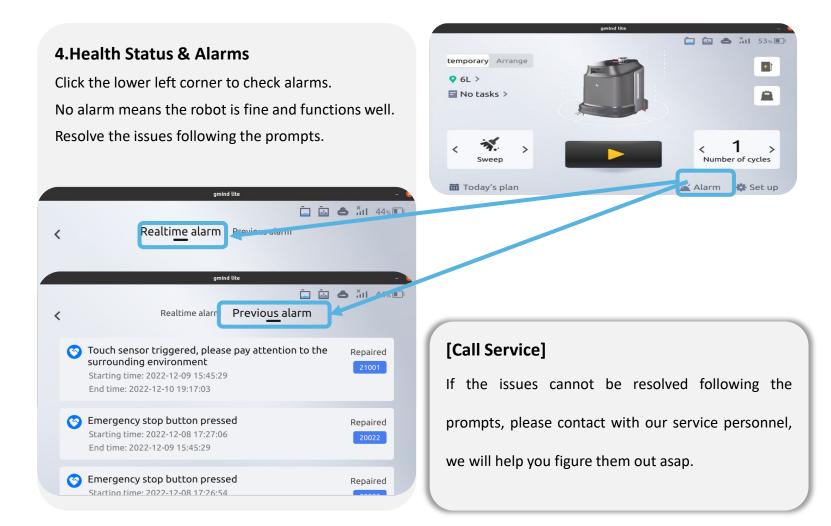


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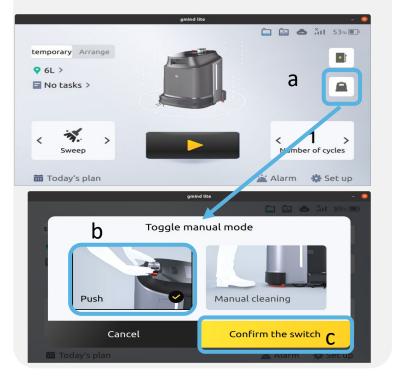
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1.Switch to Manual Push Mode Click [a]Manual Mode, [b]Push, [c]Confirm



2. Move Manully

Hold the robot with your hands, move it to storage place.



3.Power Off

Turn off the switch to "**O**"and turn off the circuit breaker.



4.Open Top Lid

Press down"Open" button to open the

top lid.



5.Take out water tank/dust tank

Take out the water tank / dust tank and

clean them.

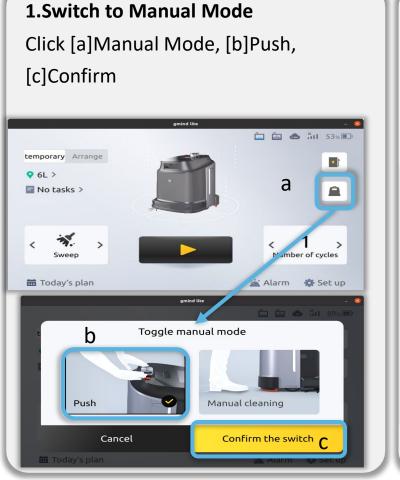


[Notice for long-term storage]

Clean the consumables if you want to store the robot for a long time.

Empty clean water tank and wastewater tank, remove rubber strips of squeegee.

Store them together in dry and ventilated place after cleaning.



2. Move Robot to charging dock



3.Start Charging

Insert the plug into the port of robot, then connect the plug with power supply.

The red indicator flashes when charging

starts.



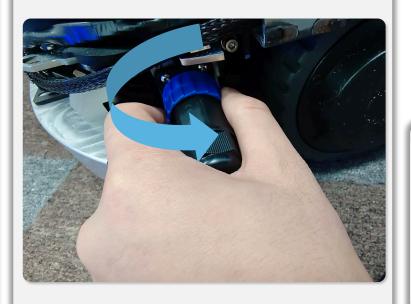
4.Fully Charged

The indicator turns green when robot is fully charged.



5.Remove Plug

Cut off power supply first, then remove plug from port.



Notice: Turn the blue coupling counterclockwise to unlock the plug.



1.Switch to Manual Mode 3.Open Top Lid 2. Move Robot to Maintenance Point Click "Manual Mode", "Push" and Press down the button "Open" to Hold the 2 sides of robot and push it to "Confirm" maintenance point. uncover the top lid. 🗖 🖾 📥 ភ័ព 53% 💷 temporary Arrange * 9 6L > а No tasks > N. > < > mber of cycles Sweep 🕍 Alarm 🛛 🏶 Set up 📅 Today's plan gmind lite Toggle manual mode b Manual cleaning Push Cancel Confirm the switch

4. Take Out Wastewater Tank & Drain

Open top lid, take out the wastewater tank and pour out the wastewater. Then clean it and put it back into robot.



5.Add Clean Water

The clean water inlet is in the upper right corner. Use hose or measuring cup to add water manually.

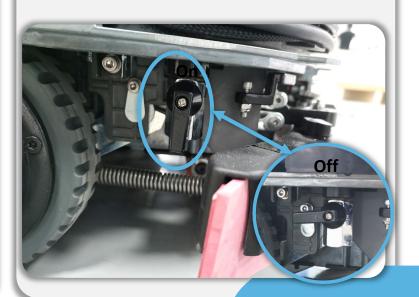
Notice: aware water spill or overflow when adding water.



6.Empty Clean Water Tank

There is a valve behind the left wheel that is for draining clean water.

Move robot to a proper place and turn on the valve to empty the water tank if necessary. (It takes 3-4 minutes)



1.Select Cleaning Mode

Select a cleaning mode (scrubbing, dust mopping, sweeping, vacuuming).



2.Switch to Manual Mode

Click "Manual Mode", "Manual Cleaning" and "Confirm"



3.Manual Operation

Push robot slowly to do manual cleaning operation.



4.End Manual Operation Click "Manual Mode", "Push" and "Confirm"



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5.Clean Waster Stain

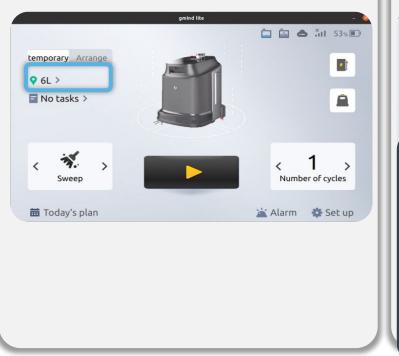
To prevent water contamination after manual mode ends, suction & squeegee will keep working for a while. Continue to slowly push robot for 1-2 meters to clean the water stain.

 The suction and squeegee keep working 30 seconds of delay (by default)



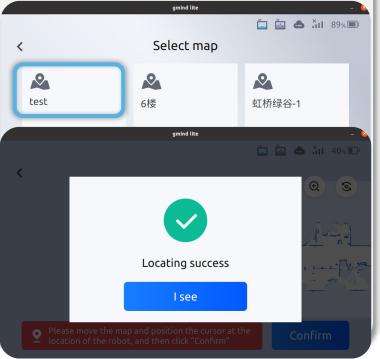
1.Choose Map

Map is the area you want the robot to clean.



2.Check Position

Check the robot's position. If the position is wrong, choose the map again and do re-positioning.



3.Choose Task

Choose a cleaning task that matches with the map(refer to the red frame below).



4. Choose cleaning mode

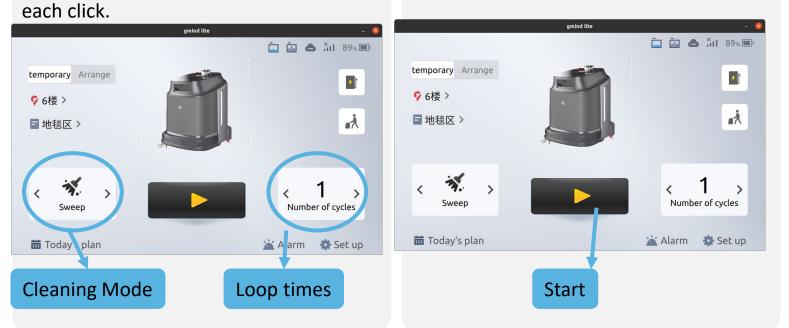
Four options:scrubbing, dust mopping, sweeping, vacuuming

Cleaning mode will be switched after

5.Start auto operation

Click start.

6.Auto-operation interface



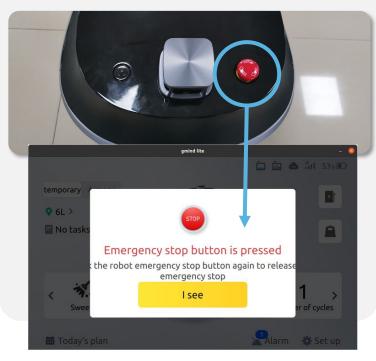


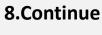
7.Pause

Press the red button to execute an emergent stop.

The robot re-starts 30 seconds after an emergent stop.

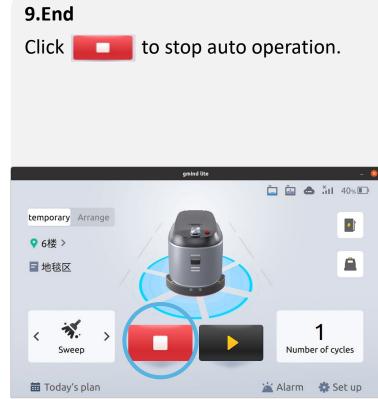
Click Confrim to retain the stop.





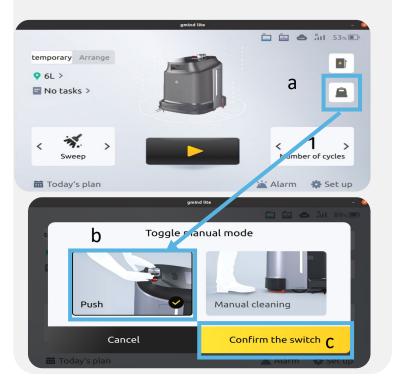
Click **to** continue auto operation.





1.Switch to Manual Mode

Click "Manual Mode", "Push" and "Confirm"



2.Move Robot

Move robot to the area to be cleaned.



3.Re-locating

- Click **?** and select the map for relocating.
- A message will pop out to tell whether locating succeeds or fails.
- If locating failed, please check the map or move robot to other place and try again.



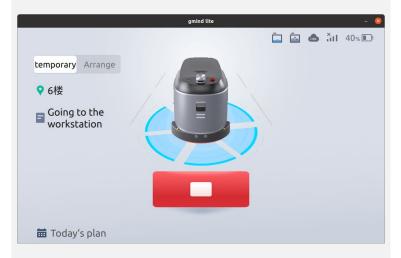
1.Back to Charging Dock Click the "**Back to Charging Dock**" icon, robot will go back to the charging pile automatically.

Note: locating should be correct before clicking the icon.

2.Back to Charging Pile

The interface changes after clicking "**Back to Charging Dock**" (refer to the figure below).

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3.Docking

After auto-docking succeeded, the screen will show current charging status. On-charging: the light indicator of charging pile and light strip of robot turn green. (Fig. 2)

Fully charged: Light strip of robot turns blue (Fig. 3)



Fig. 1:Not charged



Fig. 2:Charging



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Fig. 3:Fully Charged

Fig. 3:Charging Icon

1.Switch between Vacuum and Scrubbing

A dust tank is for vacuum cleaning. A wastewater tanks is for scrubbing mode.

• Open the top lid to change the tank.



2.Switch between Sweep and Dust Mop A bristle roller brush is for sweep mode. A cloth roller brush is for dust mop cleaning.

• Take out the roller brush assembly from right side of the robot and replace the sub-brush.

